



# Radar Level Transmitter

# ARL5000 Series





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Sincerely thank you for buying Radar level transmitter!

This manual introduces the application, feature, function, installation and setup of Radar level transmitter level transmitter so that users can know, install, use and maintain this instrument.

#### 2. Overview

ARL5000 is characterized by 26G electromagnetic wave and the measurement will be not affected by the influence of noise, water vapor, temperature, pressure, dust, gas volatilization etc. With excellent anti-interference ability, it can work effectively in harsh environments.

Equipped with a new micro processor, ARL5000 is more ideal in rate signal analysis, processing capacity, which greatly improves the stability and accuracy of measurement. ARL5000 features in non-contact level measurement, simple structure and easy installation and it can be widely used in complicated working conditions such as reaction kettle, solid liquid silo, high temperature and high pressure.

#### 3. Measuring Principle

The narrow microwave pulses are emitted via an antenna, reflected from the measured media surface and then received by antenna system again. The received signals are transmitted to electronic circuit and some are automatically converted to level signals. (The process, the electromagnetic wave reaches the target and is reflected back to the receiver, occurs instantly. because the microwave travels very fast.)



Measurement datum plane: Screw thread Bottom and Flange Sealing Surface

## Note: When the radar level is used, please make sure that the highest material level can not reach the measuring blind are (As shown in D area).

#### 4. Features

- > Non-contact radar, free of wear and pollution
- > Small measuring blind area, ideal for small tank measurement
- > Not affected by working conditions such as corrosion, foam, noise, water vapor, dust, vacuum, etc.
- Small antenna, simple installation
- > Shorter wavelength, better reflection on inclined solid surface
- > High signal-to-noise ratio, excellent performance under fluctuating conditions
- > High frequency, ideal for the measurement of solid and dielectric constant
- Small beam angle & focus energy to enhance radar echo capacity
- Support HART / RS485 communication for on-site debugging

## ARL5000 Operation Manual **5. Products**



#### OP5000.1.1.7.R1ENG

![](_page_4_Picture_2.jpeg)

# Type: H1 (\$\overline{76}\$) / H2 (\$\overline{96}\$) / H3 (\$\overline{9121}\$) Application: Easily Condensed or Dust Process Vessels Range: 0-40 m Accuracy: +/-15 mm Temp. : -40~130 °C / -40~230 °C Pressure: -1.0~3 bar / -1.0~16 bar

Connection: Universal Flange / Fixed Flange Antenna Material: S.S. 316L

Flange Material: S.S. 304 (S) / S.S. 316L (O)

Beam Angle lpha: 12° / 8° / 6°

Antenna Size:  $\phi$  76 /  $\phi$  96 /  $\phi$  121 mm

Antenna Length: 205 / 290 / 610 mm

Purge Device: Option

Flange: DN80-DN150

30mm	Accuracy	
15mm —		
0	1m	40m
-15mm —		
-30mm	4	

## ARL5000 Operation Manual 6. Technical Parameters

Measure Principle	: Radar	<ul> <li>Keypad</li> </ul>	: 4 internal keys for programming
<ul> <li>Measure Range</li> </ul>	: 0-70 m	<ul> <li>Unit</li> </ul>	: ft, in, m, cm, mm
<ul> <li>Display</li> </ul>	: 4 Digit LCD with Bargraph	Process Temperature	: -40~130 °C (Standard)
Resolution	: 1 mm / 0.003 ft		-40~230 °C (Optional)
Accuracy	:+/-3 mm…+/-15 mm	Process Pressure	: -1.0~40 bar G (Max. )
<ul> <li>Blind Area</li> </ul>	: The end of antenna	Max. Cable Length	: 8 m (for single cavity housing)
• Beam Angle $\alpha$	: 20° / 18° / 14° / 12° / 8° / 6°	Power Supply	: 16-26 VDC (2 wires)
Measuring Interval	: >1s (Dependent on configuration setting)		: 24 VDC ± 10% (4 wires)
<ul> <li>Adjustment Time</li> </ul>	: >1s (Dependent on configuration setting)		: 90-253 VAC, 50 / 60 Hz (4 wires)
<ul> <li>Ambient Temperature</li> </ul>	: -40~80 °C	Power Consumption	: 22.5 mA / 1W (Max. )
Relative Humidity	: 0-95% RH	Current Output	: 4-20 mA (2 wires, 4 wires)
Permittivity DK	: >1.4	Load	: Rohm=(VDC-16) * 50
<ul> <li>Ambient Temp. Effect</li> </ul>	: 3 mm / 10 K, Max. 10 mm	Resolution	: 1.6 μΑ
<ul> <li>Gas Pressure Effect</li> </ul>	: 0.22 % (Air: 10 bar / 20 °C)	Alarm Current	: No change / 20.5 mA / 22 mA / 3.9 mA
<ul> <li>Material</li> </ul>		Damping	: 0-40 s
Antenna	: PTFE / PFA / S.S. 316L	Communication	: HART signal (Compatible) (Standard)
Process Connection	: PP / PTFE / S.S. 304 / S.S. 316L / S.S +coated		: RS485 (MODBUS Protocol) (Optional)
Housing	: Aluminum Alloy	<ul> <li>Data Storage</li> </ul>	: Operation parameters and totalization
Process Connection	: 1-1/2" NPT / G 1-1/2" Max. : 16 bar		date are stored by EEPROM for more
	: Flange (DN50-DN150) Max. : 40 bar		than 10 years
	: Universal Flange (DN80-DN150) Max. : 3 bar	EMI / RFI Effect	: Follow SAMA PMC 33.1 from 20 to 1000
<ul> <li>Protection Class</li> </ul>	: IP67		MHz and for field strengths up to 30 V/m
	: Explosion Proof, Ex d IIC T6	Vibration Resistance	: 20-2000 Hz, 1 (m/s <sup>2</sup> ) <sup>2</sup> /Hz
	: Intrinsically Safe, Ex ia IIC T6	Cable Entry	: Standard: M20, Option: 1/2" NPTF

Please reserve enough installation space and try to avoid strong shock installation occasions.

A. Vaulted Tank

Be installed in the 1/4 or 1/6 of the vaulted tank diameter

Note: The minimum distance from the tank wall should be 200 mm.

Note: 1Datum plane

2 The tank center or axis of symmetry

![](_page_6_Picture_9.jpeg)

B. Tapered Tank

Be installed in the flat-top middle of tapered tank to ensure that the bottom of the tank is measured

![](_page_6_Figure_12.jpeg)

## ARL5000 Operation Manual C. Stacking Tank

The antenna should be perpendicular to the material surface. If the material surface is not flat and the pile angle is large, a universal flange can be used to adjust the horn angle so that the horn can point at the material surface as much as possible.

![](_page_7_Figure_3.jpeg)

Note: Inclined solid surfaces will cause echo attenuation and even signal loss.

D. Be not installed in the middle of vaulted or round tank roof. Because multiple echoes can be concentrated at the top, and the echo signal may be larger than the signal threshold of the true echo.

![](_page_7_Figure_6.jpeg)

E. Be not installed above the material inlet or agitator, and outdoor protection measures are necessary such as sunshade, rainproof, etc.

![](_page_8_Figure_3.jpeg)

F. If obstacle signals exist in the tank, a reflector can be added to refract them away to ensure normal measurement.

![](_page_8_Figure_5.jpeg)

G. Interference occurs when there are obstacles, such as ladder, heating device, agitators, etc. in the area radiated by the emitted microwave beam. It is recommended the way of by-pass pipe installation.

![](_page_9_Figure_3.jpeg)

By-pass Pipe Requirements:

- Metal tube (optional plastic liner): to prevent radar signals from penetrating the tube wall to generate interference echoes
- Pipe diameter in uniform, and the difference between horn antenna diameter and waveguide inner diameter should be as little as possible
- > Keep waveguide pipe inner wall smooth, the average surface finish of  $Rz \le 6.3 \mu m$ .
- > The way of by-pass pipe installation can not be used for measurement of adhesive medium
- H. The way of waveguide pipe installation is recommended for frothy liquid or big fluctuations of level in the tank.

![](_page_9_Figure_10.jpeg)

Waveguide Tube Requirements:

- Metal tube (optional plastic liner): to prevent radar signals from penetrating the tube wall to generate interference echoes
- Tube diameter in uniform, the difference between horn antenna diameter and waveguide tube inner diameter should be as little as possible
- > Keep waveguide tube inner wall smooth, the average surface finish of  $Rz \le 6.3 \mu m$
- > Equal pressure holes should be reserved to ensure the same liquid level inside and outside the waveguide tube
- > The way of waveguide tube installation can not be used for measurement of adhesive medium
- Venthole diameter of 5-10 mm

I. Nozzle Height Requirements: The reflected wave generated by the end of the nozzle may affect the measurement result. So generally the horn antenna needs to stick out of the nozzle.

The nozzle height must ensure that the distance of antenna sticking into the tank can not be less than 10 mm.

![](_page_10_Figure_4.jpeg)

However, if the measured medium is with good reflective characteristics, the connected pipe can be longer than antenna length. And the standard connected pipe length is shown as below chart. In this case, the end of the connected pipe can never have burr and other protrusion and needed to be smoothed. If necessary, the 'False echo memory (false echo learning)' function can be used to remove weak reflection from the end of the connected pipe.

![](_page_10_Figure_6.jpeg)

J. Avoid measured liquid level reaching the blind zone, resulting in incorrect measurement

K. If the process temperature is high, an insulation layer must be added outside the tank to avoid electronics overheating inside the instrument due to heat radiation or heat convection, but the insulation layer must not exceed the device neck.

## ARL5000 Operation Manual 8. Electrical Connection

![](_page_11_Figure_2.jpeg)

![](_page_11_Figure_3.jpeg)

## ARL5000 Operation Manual **9. Dimensions**

![](_page_12_Figure_2.jpeg)

![](_page_13_Figure_2.jpeg)

## ARL5000 Operation Manual **10. Start-up Display**

![](_page_14_Figure_2.jpeg)

Note: If the start-up display keeps jumping in Starting...and progress bar interface, and can not start up normally. Then please check if power supply or wiring is wrong.

#### 11. Display Mode

Two display modes are available.

![](_page_14_Figure_6.jpeg)

- If the alarm occurs, the main display interface will display alarm code, for example, e.g., E14 means weak echo or no echo, E11 means power problem, E15Room means storage issues.
- > After five minutes of user inactivity, Echo curve interface will jump to main display interface.

![](_page_15_Figure_2.jpeg)

Name	Button	Function		
Back key	BACK	Exit out of edit state Interrupt input Return to the previous menu Switch measuring value / echo curve at run time		
Up	$\square$	Change parameter value Chose display mode		
Right	$\begin{tabular}{ c c c c } \hline \begin{tabular}{ c c } \hline \begin{tabular}$	Chose programming item Chose parameter position Display parameter content		
Setting key	ENT	Enter programming state Confirm programming item Confirm parameter modification		

![](_page_16_Figure_2.jpeg)

![](_page_17_Figure_2.jpeg)

#### 14.1 Basic Settings (Medium is Liquid)

![](_page_18_Figure_3.jpeg)

![](_page_19_Figure_0.jpeg)

![](_page_19_Figure_1.jpeg)

 $\triangleright$ 

Please check whether level change fast or not, and choose Yes or No. Yes refers to that level change fast and system has a higher speed of collecting signal Press  $\blacksquare$  to enter the editing state, press  $\triangle$  and  $\triangleright$  to choose, press  $\blacksquare$  to

Press <a>> to enter the next menu.</a>

First echo setting includes five types: Normal: Do nothing to first echo (default value) Small: Decrease first echo amplititude by 10dB Big: Increase first echo amplititude by 10dB Bigger: Increase first echo amplititude by 20dB Biggest: Increase first echo amplititude by 40dB Press  $\blacksquare$  to enter the editing state, press  $\triangle$  and  $\triangleright$  to set, press  $\blacksquare$  to save the Press b to enter the next menu.

If liquid is chosen in Medium setting, the menu of 1.3.3 is "Agitated surface" setting, If level surface agitate greatly, please choose Yes, if not, choose No. Press  $\blacksquare$  to enter the editing state, press riangle and riangle to choose, press  $\blacksquare$  to Press D to enter the next menu.

If liquid is chosen in Medium setting, the menu of 1.3.4 is "Foaming" setting, if level surface is with foam, please choose Yes, if not, please choose No. Press  $\blacksquare$  to enter the editing state, press riangle and riangle to choose, press  $\blacksquare$  to

Press  $\square$  to enter the next menu.

If liquid is chosen in Medium setting, the menu of 1.3.5 is "Low DK" setting referring to the measuring setting for level DK in the range of 2-4, after choosing YES, user needs to input an accurate measured distance of empty tank, which is used to judge the tank bottom position to reduce reflection from the tank bottom. Press  $\blacksquare$  to enter editing state, press  $\triangle$  and  $\triangleright$  to choose and set parameters, press I to save the setting. Press b to enter the next menu.

If liquid is chosen in Medium setting, the menu of 1.3.6 is "Measure in tube" setting, which is used for on-site waveguide tube. Users need to enter waveguide Press  $\blacksquare$  to enter the editing state, press  $\triangle$  and  $\triangleright$  to choose and set parameters, press I to save the setting. Press 🔤 to return to Medium interface.

Press <a>> to enter the next menu.</a>

m

SENSOR

![](_page_20_Figure_2.jpeg)

#### ARL5000 Operation Manual 14.2 Basic Settings (Medium is Solid)

![](_page_21_Figure_2.jpeg)

10 s

![](_page_22_Figure_2.jpeg)

In order to suppress the fluctuation of the measuring value caused by the fluctuation of the liquid level, an appropriate damping time can be set to ensure sufficient response time on the measurement and allow the sensor to reflect the changed measurement value after the time delay. The factory default is set as 10s.

Press  $\blacksquare$  to enter the editing state, press  $\bigtriangleup$  and  $\bowtie$  to set, press  $\blacksquare$  to save the setting.\_

Press  $\blacktriangleright$  to enter the next menu.

SENSOR

![](_page_23_Figure_2.jpeg)

#### ARL5000 Operation Manual 14.3 Basic Settings (Medium is Micro DK)

![](_page_24_Figure_2.jpeg)

![](_page_25_Figure_2.jpeg)

![](_page_26_Figure_1.jpeg)

![](_page_26_Figure_2.jpeg)

Main display interface will display sensor tag; user can set sensor tag to distinguish more than one radar level gauges. Press  $\blacksquare$  to enter the editing state, press  $\triangle$  and  $\triangleright$  to set, press  $\blacksquare$  to save the setting.

Double press e to return to the main display interface.

## ARL5000 Operation Manual **14.4 Display Setting**

m

SENSOR

![](_page_27_Figure_1.jpeg)

#### ARL5000 Operation Manual 14.5 Diagnostics Setting

![](_page_28_Figure_1.jpeg)

Service Info

6.50

SENSOR

BACK

m

![](_page_29_Figure_2.jpeg)

![](_page_29_Figure_3.jpeg)

## ARL5000 Operation Manual **14.6 Service Setting**

![](_page_30_Figure_1.jpeg)

 $\triangleright$ 

![](_page_31_Figure_2.jpeg)

![](_page_32_Figure_1.jpeg)

![](_page_33_Figure_2.jpeg)

![](_page_34_Figure_1.jpeg)

#### 14.7 Information Menu

![](_page_34_Figure_3.jpeg)

#### OP5000.1.1.7.R1ENG

Threshold setting (Note: this menu needs to be set by professionals) The threshold setting is used to set the threshold value of the effective echo. The larger the threshold set, the stronger the effective echo amplitude needed on the site, which is more conducive to removing small signal clutter interference. But please note: If the modified threshold is bigger than the effective echo amplitude, it will cause misunderstanding wave result.

This menu includes the echo threshold and the envelope level. The default of the echo threshold amplitude is set as 60mV, and the envelope level is set as 10mV by default.

Press  $\blacksquare$  to enter the editing state, press  $\bigtriangleup$  and  $\vartriangleright$  to set, press  $\blacksquare$  to save the setting.

Press 🔤 to return.

Main display interface This interface shows host variables (level / distance etc.), units, sensor tag, and percentage bar, can be switched to echo curve display. Press end to enter the setting menu.

Information Information items include: sensor serial number, date of manufacture and software version. Press 🖻 to move the cursor, as the cursor is pointing at Info, press 🖻 to enter info submenu.

Sensor type and serial number Sensor type serial number is by factory default, users can not change. Press to enter the next menu.

Date of manufacture and Software version Date of manufacture and Software version are set as factory default, users can not change. Press I to exit Info menu.

#### ARL5000 Operation Manual 15. MODBUS-RTU Protocol

#### **15.1 Protocol Introduction**

ARL5000 applies this standard MODBUS-RTU mode. MODBUS: MODBUS-RTU mode Baudrate: 9600 bps Parity: None Databit: 8 Stopbit: 1 Communication address: 01-127 Function Code: 03, to read Register value. Function Code: 06, to modify Register value.

#### 15.2 Input Register Table

No.	Name	Function Code	Data type	Address	Data Length	Unit
1	Measured distance	03	Float	Ox0000	Ox0001	СМ
2	Measured distance	03	Float	Ox0001	Ox0001	MM
3	Level distance	03	Float	Ox0002	Ox0001	СМ
4	Level distance	03	Float	Ox0003	Ox0001	MM
5	Measuring status	03	Float	Ox0004	Ox0001	Hexadecimal signal strength (dB)
6	Upper range value	03/06	Float	Ox0005	Ox0001	СМ
7	Blind area	03/06	Float	Ox0006	Ox0001	СМ
8	Min. Adjustment	03/06	Float	Ox0007	Ox0001	СМ
9	Max. Adjustment	03/06	Float	Ox0008	Ox0001	СМ

#### 15.3 Examples

1. Read 10 Register values from 0x0000: Sending Command: (MODBUS Address) + (Function Code) + (Register Address) + (Register Length) + (CRC Check Code) Ox0000 Ox000A 01 03 Automatic generation Receiving data: (MODBUS Address) + (Function Code) + (Data Digit) + (Register Data) + (CRC Check Code) 01 03 14 XX--XX (20byte) Automatic generation 2. Modify the instrument parameters; the upper range of modification is 10 m (1000 cm) Sending Command: (MODBUS Address) + (Function Code) + (Register Address) + (Register Data) + (CRC Check Code) 01 Ox0005 03E8 Automatic generation 06 Receiving Data: (MODBUS Address) + (Function Code) + (Register Address) + (Register Data) + (CRC Check Code) Ox0005 03E8 Automatic generation 01 06